

Non-Uniform Sparsest Cut and Metric Embeddings¹

- The final cut problem we will look at is a generalization of the *sparsest cut* problem we saw last time: it's called the *non-uniform sparsest cut* problem, or the *generalized sparsest cut* problem. The input, as usual, is an undirected graph $G = (V, E)$ with non-negative costs $c(e)$ on edges. Along with this, we are now given *pairs of terminals* or *demand pairs*: $\{s_i, t_i\}$ with $1 \leq i \leq k$. The sparsity of a subset of vertices $S \subseteq V$ with respect to these demand pairs is defined to be the **ratio** $\Phi(S) := \frac{\sum_{e \in \partial S} c(e)}{|\{i: \{s_i, t_i\} \cap S = 1\}|}$. That is, it is the ratio of the cut edges and the number of demand pairs separated by this set S . This generalizes the notion from last time which can be seen as the special case of *all* pairs being demand pairs. The objective is to find the cut $S \subseteq V$ of minimum sparsity. We use Φ_G^* to denote this minimum value.
- **Linear Programming Relaxation.** The LP relaxation is similar to the uniform sparsest cut problem; the only difference is that the sum of distances between only the terminal pairs is set to 1.

$$\text{lp} := \min \sum_{e=(u,v) \in E} c(e) d_{uv} \quad (\text{General Sparsest Cut LP})$$

$$d_{uw} \leq d_{uv} + d_{vw}, \quad \forall i \in F, \forall \{u, v, w\} \subseteq V \quad (1)$$

$$d_{vv} = 0, \quad \forall v \in V \quad (2)$$

$$\sum_{i=1}^k d_{s_i t_i} = 1$$

- **Cut Metrics, ℓ_1 -metrics, and Metric Embeddings.** The solution to ([General Sparsest Cut LP](#)) returns a distance function d between all pairs of vertices, and thus (V, d) forms a *finite metric space*; it is precisely a finite set of points equipped with a distance function. And this distance function minimizes a certain objective. We now notice that the sparsest cut problem (and in fact many cut problems) are precisely a question of finding a distance function d^* “from a certain special class” which minimizes the same objective. The approximation algorithm follows by taking the “general” metric returned by ([General Sparsest Cut LP](#)) and mapping/embedding into this “special class” that “warps” the distance function as little as possible.

We now discuss this special class of metric/distance function. Fix a subset $S \subseteq V$. The **elementary cut-metric** (V, d_S) induced by this subset is simply defined as

$$d_S(u, v) = \begin{cases} 1 & \text{if } |S \cap \{u, v\}| = 1 \\ 0 & \text{otherwise} \end{cases}$$

¹Lecture notes by Deeparnab Chakrabarty. Last modified : 18th Mar, 2022

These have not gone through scrutiny and may contain errors. If you find any, or have any other comments, please email me at deeparnab@dartmouth.edu. Highly appreciated!

Definition 1 (Cut Metric). A metric/distance function $d : V \times V \rightarrow \mathbb{R}_{\geq 0}$ is a *cut metric* if it can be expressed as a *non-negative, linear* combination of elementary cut metrics. That is, there exists $\lambda_S \geq 0$ for all $S \subseteq V$ such that for any $u, v \in V \times V$, we have

$$d(u, v) = \sum_{S \subseteq V} \lambda_S d_S(u, v)$$

We use CUT to denote the cone^a of all cut-metrics.

^aA cone is a subset C of \mathbb{R}^k where $x \in C$ implies $\alpha x \in C$ for any $\alpha \geq 0$, and $x \in C, y \in C$ implies $x + y \in C$. When V is finite, the distance function can be thought of as an $\binom{V}{2}$ -dimensional vector.

The next observation asserts that the optimum sparsity is obtained by minimizing the “ratio function” over the special class of cut-metrics.

Observation 1. For any graph G ,

$$\Phi^*(G) = \min_{d \in \text{CUT}} \frac{\sum_{(u,v) \in E} c(u, v) d(u, v)}{\sum_{i=1}^k d(s_i, t_i)} \quad (3)$$

Exercise: 🍷 Prove the above. Note that Φ^* is precisely the minimum when d is an elementary cut metric. Show that taking non-negative linear combinations cannot decrease the RHS.

The next observation connects cut metrics to more well-known metrics.

Definition 2 (ℓ_1 -Metric). A metric/distance function $d : V \times V \rightarrow \mathbb{R}_{\geq 0}$ is an ℓ_1 *metric* if there exists a map $\phi : V \rightarrow \mathbb{R}^h$ for some non-negative integer h such that for every pair of points $u, v \in V \times V$, we have

$$d(u, v) = \|\phi(u) - \phi(v)\|_1 = \sum_{i=1}^h |\phi(u)[i] - \phi(v)[i]|$$

We use \mathcal{L}_1 to denote the cone of all ℓ_1 metrics on V .

The next lemma shows that CUT and \mathcal{L}_1 are the same.

Lemma 1 (ℓ_1 -Metric). For any (V, d) with $d \in \text{CUT}$, there is a mapping $\phi : V \rightarrow \mathbb{R}^h$ for some h , such that $\|\phi(u) - \phi(v)\|_1 = d(u, v)$ for all pairs u, v . Conversely, given a mapping $\phi : V \rightarrow \mathbb{R}^h$, there exists $d \in \text{CUT}$ such that $d(u, v) = \|\phi(u) - \phi(v)\|_1$ for all pairs u and v . The second mapping is polynomial time computable and has $\lambda_S > 0$ for at most nh sets.

Proof. Suppose $d \in \text{CUT}$ and let $d = \sum_S \lambda_S d_S$. That is, for any pair u, v , $d(u, v)$ equals the sum of λ_S for all subsets S separating u and v . Now define a mapping on $h := |\{S : \lambda_S > 0\}|$ coordinates, as follows: $\phi(u)[S] := \lambda_S \cdot \mathbf{1}_{u \in S}$. That is, the S th coordinate of $\phi(u)$ is λ_S if $u \in S$, otherwise it is

0. Note that for any pair u, v , $\|\phi(u) - \phi(v)\|_1$ equals the sum of λ_S for all S separating u and v . That is, $\|\phi(u) - \phi(v)\|_1 = d(u, v)$.

For the converse, we have a mapping $\phi : V \rightarrow \mathbb{R}^h$. For every coordinate, we associate h subsets as follows. Fix a coordinate i . Order the vertices as $\phi(u_1)[i] \leq \phi(u_2)[i] \leq \dots$. The sets with positive λ_S are precisely $\{u_1, \dots, u_t\}$ for $t = 1, \dots, h$, and define $\lambda_S = \phi(u_t)[i] - \phi(u_{t-1})[i] \geq 0$ for $S = \{u_1, \dots, u_t\}$. Also define $\phi(u_0)[i] = 0$. It is easy to check that $d(u, v) = \|\phi(u) - \phi(v)\|_1$. \square

Therefore, the above lemma and (3) implies $\Phi^* = \min_{d \in \mathcal{L}_1} \frac{\sum_{(u,v) \in E} c(u,v)d(u,v)}{\sum_{i=1}^k d(s_i, t_i)}$. The final definition we need is the following.

Definition 3 (Metric Embedding). Given two metric spaces (V, d) and (U, ℓ) , a mapping $\phi : V \rightarrow U$ is an **embedding** if it is injective, that is, $x \neq y \Rightarrow \phi(x) \neq \phi(y)$. This metric has *dilation* at most $\alpha \geq 1$ and *contraction* at most $\beta \geq 1$ if for any two vertices $u, v \in V \times V$, we satisfy

$$\forall u, v \in V \times V : \frac{d(u, v)}{\alpha} \leq \ell(\phi(u), \phi(v)) \leq \beta \cdot d(u, v) \quad (4)$$

The parameter $\rho = \alpha \cdot \beta$ is the *distortion* of this embedding.

At times, we only care about the dilation/contraction only for a subset of vertices; that is, (4) holds only for $u, v \in S \times S$. We then say the metric embedding has distortion ρ when restricted to the subset S . Another thing before we move on. One could think of ϕ as an algorithm mapping V to U . Many embeddings are described as a *randomized* map/algorithm, and one has (4) holding only with high probability. First, if the probability of error $\ll \frac{1}{|V|^2}$, then union bounding and the probabilistic method implies there exists one embedding with distortion ρ . Second, for most algorithmic purposes, this randomized mapping suffices.

- Finally, we connect to generalized sparsest cut.

Theorem 1. Let (V, d) be a general metric on the vertices of the graph G . Let $S := \{s_i, t_i : 1 \leq i \leq k\}$. Suppose there is a metric embedding $\phi : V \rightarrow \mathbb{R}^h$ for $h = \text{poly}(n)$ into \mathcal{L}_1 , with dilation^a α wrt S , and contraction 1 with respect to V . Furthermore, assume this embedding can be obtained in polynomial time. Then, there is an α -approximation to the non-uniform sparsest cut problem.

^ait is allowed to be randomized and succeed with high probability

Proof. Given an instance of the non-uniform sparsest cut problem, solve (General Sparsest Cut LP) to obtain a metric space (V, d) with $\sum_{i=1}^k d(s_i, t_i) = 1$. Next, use the embedding algorithm which promises the metric embedding $\phi : V \rightarrow \mathbb{R}^h$ with the property that

$$\forall u, v \in S \times S : d(u, v) \leq \alpha \cdot \|\phi(u) - \phi(v)\|_1 \quad \text{and} \quad \forall u, v \in V \times V : d(u, v) \geq \|\phi(u) - \phi(v)\|_1$$

For the time being, let $\|\phi(u) - \phi(v)\|_1$ be called $\ell(u, v)$. Then observe that

$$\Phi(\ell) := \frac{\sum_{(u,v) \in E} c(u, v)\ell(u, v)}{\sum_{i=1}^k \ell(s_i, t_i)} \leq \alpha \cdot \frac{\sum_{(u,v) \in E} c(u, v)d(u, v)}{\sum_{i=1}^k d(s_i, t_i)} = \alpha \cdot \text{lp}$$

Finally, we use [Lemma 1](#) (conversely part) to obtain a cut metric $d \in \text{CUT}$ with $\ell(u, v) = d(u, v) = \sum_{S \subseteq V} \lambda_S d_S(u, v)$ with S ranging over at most $nh = \text{poly}(n)$ subsets. Choosing the S among them with smallest $\Phi(S)$ would have sparsity at most $\Phi(\ell)$ which is at most $\alpha \cdot \text{lp}$. Note that if the embedding was randomized, then the set S returned would have sparsity $\leq \alpha \cdot \text{lp}$ with probability $\geq 1 - \frac{1}{\text{poly}(k)}$. \square

- **Metric Embedding Results.** The above discussion, and in particular [Theorem 1](#) delegates all the “hard work” to finding metric embeddings of a general metric into \mathcal{L}_1 with low distortion. But such questions have been studied by mathematicians for almost a century, and therefore one can “piggy-back” on such results. The following theorem of Bourgain (stylized to capture distortion with respect to S) immediately implies a $O(\log k)$ -approximation for the general sparsest cut problem.

Theorem 2 (Bourgain’s Theorem, the Terminal Version). Given any metric space (V, d) and a set $S \subseteq V$ of size at most k , there is a mapping $\phi : V \rightarrow \mathbb{R}^{O(\log^2 k)}$ such that with high probability, we have that for any pair of vertices u and v , $\|\phi(u) - \phi(v)\|_1 \leq d(u, v)$ and for any pair $u, v \in S$, $d(u, v) \leq O(\log k) \|\phi(u) - \phi(v)\|_1$.

In the next lecture note, we see a proof of the above theorem using in fact one of the techniques we saw for the multicut problem.

Notes

After the seminal paper [4] of Leighton and Rao, there were many works on the generalized sparsest cut problem. The first was the paper [3] which gave an $O(\log C \log k)$ approximation where C is the sum of edge capacities. Any ρ -approximate algorithm for the multicut problem can be used to give an $O(\rho \log k)$ -approximation for the generalized sparsest cut (it is a nice exercise to figure this out). This was observed in the paper [2] by Garg, Vazirani and Yannakakis which also gave a $O(\log k)$ -approximation for multicut. One could thus obtain an $O(\log^2 k)$ -approximate algorithm for the generalized sparsest cut problem. See also the paper [6] for a more general $O(\log^2 k)$ -approximation.

The idea of using metric embeddings to solve these style of cut problems are from the seminar paper [5] by Linial, London, and Rabinovich. This paper and also the paper [1] by Aumann and Rabani describe the $O(\log k)$ -approximation to the generalized sparsest cut problem using the version of Bourgain’s theorem stated above.

References

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